

AS2070: Aerospace Structural Mechanics Module 1: Elastic Stability

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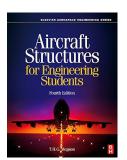
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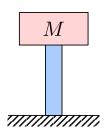
Chapters 1-3 in Brush and Almroth (1975).



 $\begin{array}{c} Chapters \ 7\text{-}9 \\ in \ Megson \ (2013) \end{array}$

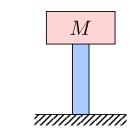
Structural Stability: What?

 \bullet Consider supporting a mass M on the top of a rod.

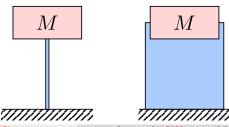


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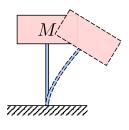


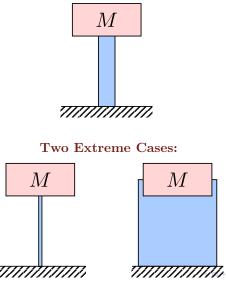
Two Extreme Cases:



Structural Stability: What?

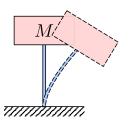
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- Collapse is imminent on at least one!



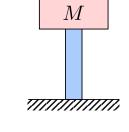


Structural Stability: What?

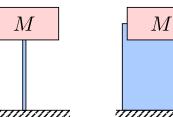
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How can we mathematically describe this?



Two Extreme Cases:



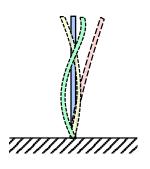
Structural Stability: Perturbation Behavior

Perturbation Behavior

Key insight we will invoke is behavior under **perturbation**:

How would the system respond if I slightly perturb it?

- Mathematically, by perturbation we mean any change to the system's configuration.
- In this case, this could be different deflection shapes.



Structural Stability: Perturbation Behavior

Perturbation Behavior

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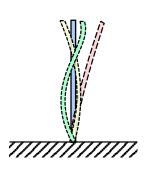
How would the system respond if I slightly perturb it?

- Mathematically, by perturbation we mean any change to the system's configuration.
- In this case, this could be different deflection shapes.

Question (Slightly more specific)

What will the system tend to do if an arbitrarily small magnitude of perturbation is introduced?

- Will it tend to return to its original configuration?
- Will it blow up?
- Will it do something else entirely?



Introduction

What do these words mean? Elastic \rightarrow Reversible \rightarrow Conservative

Conservative System

• The restoring force of a conservative system can be written using a gradient of a **potential** function:

$$F = -\nabla U$$
.

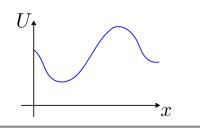
Equilibrium

• System achieves equilibrium when $\underline{F} = \underline{0}$, i.e.,

$$\nabla U = 0.$$

1D Example

Consider a system whose configuration is expressed by the scalar x and the potential is as shown.



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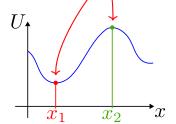
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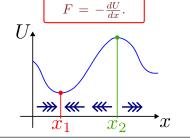
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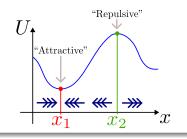
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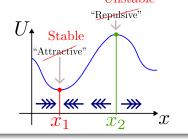
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1D Example

Consider a system whose configuration is expressed by the scalar x and the potential is as shown. Unstable

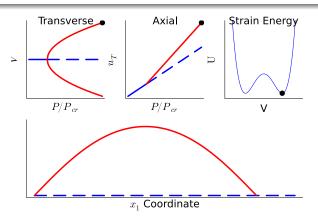


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Introduction

1.2. Bifurcation

A system is said to have **undergone a bifurcation** if its state of stability has changed due to the variation of some parameter.

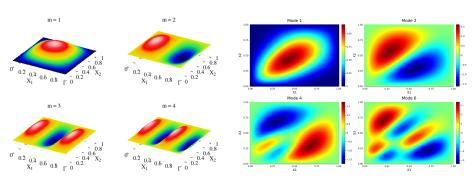


Example: A pinned-pinned beam undergoing axial loading.

1.3. Modes of Stability Loss

Introduction

The **configuration** that a system can assume as it undergoes a bifurcation is the mode of the stability loss.



Example: Thin plate (pinned) under axial loading

Example: Thin plate (pinned) under shear loading

References I

- [1] D. O. Brush and B. O. Almroth. Buckling of Bars, Plates, and Shells, McGraw-Hill, 1975. ISBN: 978-0-07-008593-0 (cit. on p. 2).
- T. H. G. Megson. Aircraft Structures for Engineering Students, Elsevier, 2013. ISBN: 978-0-08-096905-3 (cit. on p. 2).

3. Class Discussions (Outside of Slides)

- Ball on a hill. 2D, 3D cases.
- Assumptions behind compression of a bar.