

AS2070: Aerospace Structural Mechanics Module 1: Elastic Stability

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January 20, 2025

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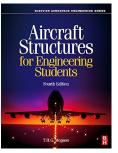
- Elastic Stability
- Bifurcation
- Modes of Stability Loss

BUCKLING OF BARS, PLATES, AND SHELLS

Don O. Brush Bo O. Almroth



Chapters 1-3 in Brush and Almroth (1975).

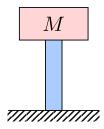


Chapters 7-9 in Megson (2013)

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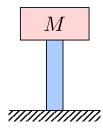
Structural Stability: What?

• Consider supporting a mass M on the top of a rod.

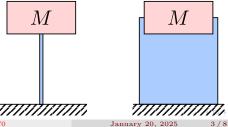


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Two Extreme Cases:

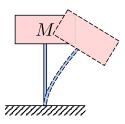


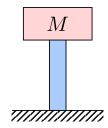
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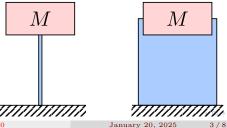
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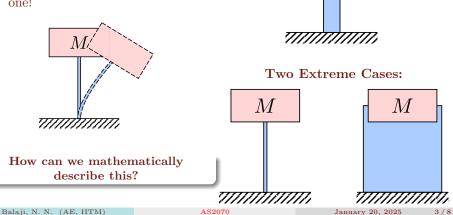


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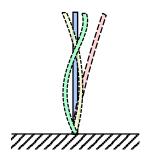
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Structural Stability: Perturbation Behavior

Perturbation Behavior

Key insight we will invoke is behavior under **perturbation**: How would the system respond if I slightly perturb it?

- Mathematically, by perturbation we mean *any* change to the system's configuration.
- In this case, this could be different deflection shapes.



Structural Stability: Perturbation Behavior

Perturbation Behavior

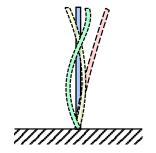
Key insight we will invoke is behavior under **perturbation**: How would the system respond if I slightly perturb it?

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Question (Slightly more specific)

What will the system tend to do if an <u>arbitrarily small</u> magnitude of perturbation is introduced?

- Will it tend to return to its original configuration?
- Will it blow up?
- Will it do **something else entirely**?



Introduction

What do these words mean?

 $\mathbf{Elastic} \rightarrow \mathbf{Reversible} \rightarrow \mathbf{Conservative}$

Conservative System

• The restoring force of a conservative system can be written using a gradient of a **potential** function:

$$\underline{F} = -\nabla U.$$

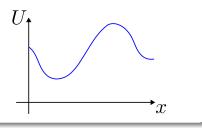
Equilibrium

• System achieves equilibrium when $\underline{F} = \underline{0}$, i.e.,

 $\nabla U = 0.$

1D Example

Consider a system whose configuration is expressed by the scalar x and the potential is as shown.



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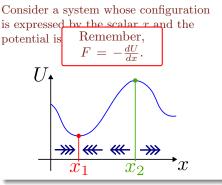
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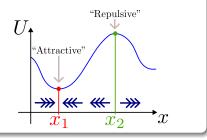
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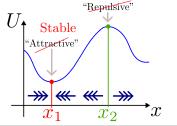
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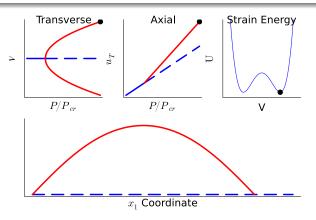
Consider a system whose configuration is expressed by the scalar x and the potential is as shown. Unstable



1.2. Bifurcation

Introduction

A system is said to have **undergone a bifurcation** if its state of stability has changed due to the variation of some parameter.



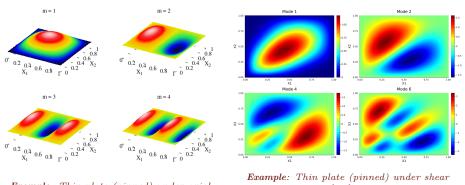
Example: A pinned-pinned beam undergoing axial loading.

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1.3. Modes of Stability Loss

Introduction

The **configuration** that a system can assume as it undergoes a bifurcation is the mode of the stability loss.



Example: Thin plate (pinned) under axial loading

loading

References I

- D. O. Brush and B. O. Almroth. Buckling of Bars, Plates, and Shells, McGraw-Hill, 1975. ISBN: 978-0-07-008593-0 (cit. on p. 2).
- T. H. G. Megson. Aircraft Structures for Engineering Students, Elsevier, 2013. ISBN: 978-0-08-096905-3 (cit. on p. 2).